

## PM3



CAN controlled power distribution module, capable of working in a matrix of units

### Specifications

Parameter	Value
8 Outputs	Switched 12V at max, continuous 20A per channel
Total Maximum Rating	160A (8 simultaneously active channels)
CAN Bus	CAN 2.0, 1Mbaud, 8 selectable addresses using configure pins
Status LED	Solid when powered up and CAN OK, Flashing when CAN is lost
Casing	Sealed Aluminium
Size	103 x 67 x 38 mm
Weight	190 grams

NOTE: Use 2 pins for each output for full current capacity.

## Connectors

ID	Connector	Loom/Mating Connector
1	TE SUPERSEAL 6437288-6	TE 3-1437290-7
2	M6 threaded power pin	M6 ring terminal (recommended)

## Pin Out

Connector	1	
Pin	Name	Function/Notes
1	High Side Driver 1	
2		
3	CAN Low	
4	CAN High	
5	Ground	
6	High Side Driver 5	
7		
8	High Side Driver 2	
9		
10	Config 3	
11	Ground	
12	High Side Driver 6	
13		
14	High Side Driver 3	
15		
16	Config 2	
17	<i>Not Used</i>	
18	High Side Driver 7	
19		
20	High Side Driver 4	
21		
22	Serial Rx	
23	Serial Tx	
24	Config 1	
25	High Side Driver 8	
26		

Connector	2	
Pin	Name	Function/Notes
1	12V Power	

Standard Id: 1Mbit at 100Hz.

Two CAN transmit messages consist of 4 words as follows:

Message 1 is for Drives 1 to 4

Message 2 is for Drives 5 to 8

Each word sends information on the related drive:

High byte      bit7 = 1 = Max current exceeded i.e. short circuit (> 100Amps)

                 bit6 = 1 = Current limit set for the channel is exceeded

                 bit5 = 1 = Load open circuit

                 Measured current high 2bits

Low byte      Measured current low 8bits

Measured current scalar: 0.1 Amps/bit

The single CAN received message sends the control information to the PM3 unit. Each message consists of 8 bytes. Each byte controls 1 of the 8 output drives. Byte 1 controls drive 1... Byte 8 controls drive 8. If the value is set to 0 then the output is off. A non 0 value sets the current limit for the output at 0.4 Amps/bit.

If the PM3 unit stops receiving valid messages, it will switch off all the drive outputs with a timeout of 500ms.

**Configuration pins and Arbitration Codes**

The configuration pins (pins 10, 16 and 24) set the arbitration codes for the PM3 unit. The pin should either be left open circuit (O/C) or connected to GND Pin1)

The following table lists the Arbitration codes for the 8 possible configuration settings.

<b>Config 1</b>	<b>Config 2</b>	<b>Config 3</b>	<b>TX Message 1 Code</b>	<b>TX Message 2 Code</b>	<b>RX Message Code</b>
O/C	O/C	O/C	0x610	0x611	0x620
Gnd	O/C	O/C	0x612	0x613	0x621
O/C	Gnd	O/C	0x614	0x615	0x622
Gnd	Gnd	O/C	0x616	0x617	0x623
O/C	O/C	Gnd	0x618	0x619	0x624
Gnd	O/C	Gnd	0x61A	0x61B	0x625
O/C	Gnd	Gnd	0x61C	0x61D	0x626
Gnd	Gnd	Gnd	0x61E	0x61F	0x627

## Dimensions

